

e-ISSN:2582-7219



# INTERNATIONAL JOURNAL OF MULTIDISCIPLINARY RESEARCH IN SCIENCE, ENGINEERING AND TECHNOLOGY

Volume 7, Issue 1, April 2024



INTERNATIONAL  
STANDARD  
SERIAL  
NUMBER  
INDIA

Impact Factor: 7.521



6381 907 438



6381 907 438



ijmrset@gmail.com



www.ijmrset.com



# The Smart Cane System for Visually Impaired and Blind People with A VoiceModule

Selva Dhivakar<sup>1</sup>, Mohammed Sameer. A J<sup>2</sup>, Arun Kumar M<sup>3</sup>, Mubashir A<sup>4</sup>, Karthick C<sup>5</sup>

UG Student, Department of Biomedical Engineering, Dhaanish Ahmed Institute of Technology, Coimbatore, Tamilnadu, India

Assistant Professor, Department of Biomedical Engineering, Dhaanish Ahmed Institute of Technology, Coimbatore, Tamilnadu, India

**ABSTRACT:** The "Smart Cane System for Visually Impaired and Blind People with Voice Module" is a technological solution aimed at enhancing the safety and independence of individuals with visual impairments. Traditional canes provide limited assistance in navigating the environment, often resulting in unforeseen obstacles using ultrasonic front object detection and potential hazards. This project proposes a smart cane equipped with ultrasonic sensors and a voice module to detect obstacles and provide real-time audio alerts to the user with the help of a voice feedback system. Utilizing Arduino Uno and GPS technology, the smart cane offers a cost-effective, responsive, and lightweight solution. Upon detecting obstacles, the system generates voice instructions to alert the user, enabling them to navigate safely. Additionally, the integration of IoT connectivity facilitates real-time monitoring of the user's location, enhancing overall safety and security. The objectives of this project include improving the quality of life for blind individuals, promoting independence, and facilitating mobility and navigation. By providing timely instructions based on the surrounding environment using a moisture sensor and Passive infrared sensor (PIR) and enabling remote control via a mobile app, the smart cane system aims to address the challenges faced by visually impaired individuals in their daily lives. Furthermore, the proposed system contributes to an enhanced healthcare environment by offering advanced features such as emergency notifications and centralized control through the Arduino microcontroller. Overall, the "Smart Cane System for Visually Impaired and Blind People with Voice Module" represents a significant advancement in assistive technology, empowering individuals with visual impairments to navigate their surroundings safely and independently.

**KEYWORDS:** GPS, Arduino UNO, IoT, Voice feedback system, Moisture sensor, Passive infrared sensor

## I. INTRODUCTION

Visual impairment poses significant challenges to individuals worldwide, impacting their mobility, independence, and overall quality of life. According to the World Health Organization, an estimated 39 million people globally are blind, with many more experiencing varying degrees of visual impairment. Among these individuals, navigating daily environments can be fraught with obstacles, leading to safety concerns and decreased confidence in independent mobility.

Traditional mobility aids, such as canes, offer essential support but often fall short in providing real-time assistance in detecting and avoiding obstacles. Consequently, there has been a growing need for innovative solutions that leverage technology to enhance the safety and autonomy of visually impaired individuals. The "Smart Cane System for Visually Impaired and Blind People with Voice Module" addresses this need by introducing a cutting-edge assistive technology designed to revolutionize mobility for the visually impaired. This system integrates state-of-the-art components, including ultrasonic sensors, a voice module, Arduino Uno microcontroller, and GPS technology, to create a comprehensive navigation aid. By harnessing ultrasonic sensors, the smart cane can detect obstacles in the user's path and provide immediate auditory alerts through a voice module. This real-time feedback empowers individuals to navigate their surroundings confidently, reducing the risk of collisions and enhancing safety. Moreover, the incorporation of GPS technology enables remote monitoring of the user's location, allowing caregivers or loved ones to provide assistance when needed. In addition to improving mobility and safety, the smart cane system aims to promote



greater independence and well-being among visually impaired individuals. By offering instructions tailored to specific environmental situations and facilitating remote control via a mobile app, the system empowers users to take control of their navigation experience. Furthermore, the integration of IoT connectivity enhances the system's functionality, enabling real-time data insights and facilitating proactive intervention in emergency situations. With features such as voice instructions, emergency notifications, and centralized control through the Arduino microcontroller, the smart cane system represents a significant advancement in assistive technology for the visually impaired.

**INTRODUCTION TO INTERNET OF THINGS:** The Internet of Things (IoT) encompasses the utilization of various control systems to manage diverse processes and machinery, aiming to reduce reliance on human labour. IoT refers to a network of physical objects, or "things," embedded with sensors, software, and other technologies. These objects are interconnected, enabling the exchange of data with other devices and systems via the Internet. In our context, IoT is employed to enable staff to interact with the stretcher and to facilitate communication through mobile applications, software technologies, signal detectors, and sensors. Additionally, IoT allows for the determination of the appropriate ward or room for patient transfer. IoT enables the display of information on LCD screens and triggers audible alerts, such as a buzzer, when obstacles are detected or during the stretcher's sterilization process. Essentially, IoT enhances the functionality and connectivity of the stretcher system, streamlining operations and improving overall efficiency.

**INTRODUCTION TO PROTEUS DESIGN SUITE:** The Proteus Design Suite, developed by Lab center Electronics Ltd, is a pivotal software tool in the realm of electronic design automation. IoT caters primarily to engineers and technicians involved in the creation of schematics and electronic prints for manufacturing printed circuit boards (PCBs). Available in multiple languages, including English, French, Spanish, and Chinese, Proteus enjoys widespread adoption worldwide. IoT its core, the suite comprises various modules, with the flagship product being a Windows application designed specifically for schematic capture, simulation, and PCB layout design. Its adaptable configurations cater to diverse design needs and microcontroller simulation requirements. Noteworthy features include an IoT router and basic mixed-mode SPICE simulation capabilities, which are indispensable for efficiently designing PCBs. One of the standout features of the Proteus Design Suite is its schematic capture functionality. This component serves a dual purpose as both a simulation tool and the initial stage in the design process for PCB layouts. By providing users with comprehensive functionality, IoT enables the creation and visualization of electronic circuits, offering a crucial step in the development process before the circuits are physically realized on PCBs.

**INTRODUCTION TO ARDUINO IOT:** The Arduino Integrated Development Environment (IoT) serves as a comprehensive platform for programming and interfacing with Arduino microcontroller boards. The Arduino Uno, a prominent board within the Arduino ecosystem, is based on the ATmega328 microcontroller and features 14 digital input/output pins, 6 analog inputs, and various components including a 16 MHz ceramic resonator, USB connection, power jack, ICSP header, and reset button. Unlike its predecessors, the Uno utilizes the Atmega16U2 as a USB-to-serial converter instead of the FTDI USB-to-serial driver chip. Subsequent revisions of the Uno, such as Revision 2 and Revision 3, introduced enhancements like additional pinouts, improved reset circuits, and compatibility features for future board iterations. These advancements ensure compatibility with various shields and peripherals, while the robust features of the Uno make IoT a versatile choice for a wide range of projects.

**INTRODUCTION TO NODMCU:** The NODMCU, powered by the ESP8266 microcontroller from Espressif Systems, is a versatile device designed to serve as a self-contained Wi-Fi networking solution, bridging existing microcontrollers to Wi-Fi networks while also supporting standalone applications. Equipped with a built-in USB connector and a variety of pin-outs, the NODMCU is easily connectable to a laptop for flashing using a micro-USB cable, akin to Arduino. Operating IoT a voltage of 3.3V, IoT boasts features such as Wi-Fi Direct (P2P) and soft-AP support, with a current consumption ranging from 10uA to 170mA. With an integrated TCP/IP protocol stack, a Ten silica L106 32-bit processor running IoT speeds of 80-160MHz, and 16MB of flash memory (expandable up to 512K), IoT offers ample capabilities. The NODMCU supports b/g/n Wi-Fi standards, with a maximum of five concurrent TCP connections, and includes 17 GPIO pins, one analog-to-digital input with 1024-step resolution, and a power output of +19.5dBm in 802.11b mode.



**INTRODUCTION TO BLYNK APP:** The Blink app, developed by Amazon, serves as a robust solution for home security and surveillance needs. IoT empowers users to remotely monitor their homes with live video streaming from Blink security cameras, enabling them to keep a close eye on their property from anywhere. The app offers real-time alerts and notifications for motion detection, ensuring that users are promptly informed of any activity in their monitored areas. Furthermore, Blink allows users to customize camera settings such as motion sensitivity and recording duration, catering to their specific security requirements. One of the standout features of the Blink app is its cloud storage options for recorded video footage. This feature ensures that users can access their surveillance recordings securely, even in the event of camera tampering or theft. By providing convenient access to stored footage, the app enhances the overall effectiveness of home security monitoring. Overall, the Blink app presents a user-friendly interface and seamless integration with Blink security cameras, offering homeowners peace of mind knowing that their properties are being monitored effectively, even when they are away from home. With its comprehensive features and reliable performance, the Blink app stands as a valuable tool in the realm of home security.

## II. EXISTING SYSTEM

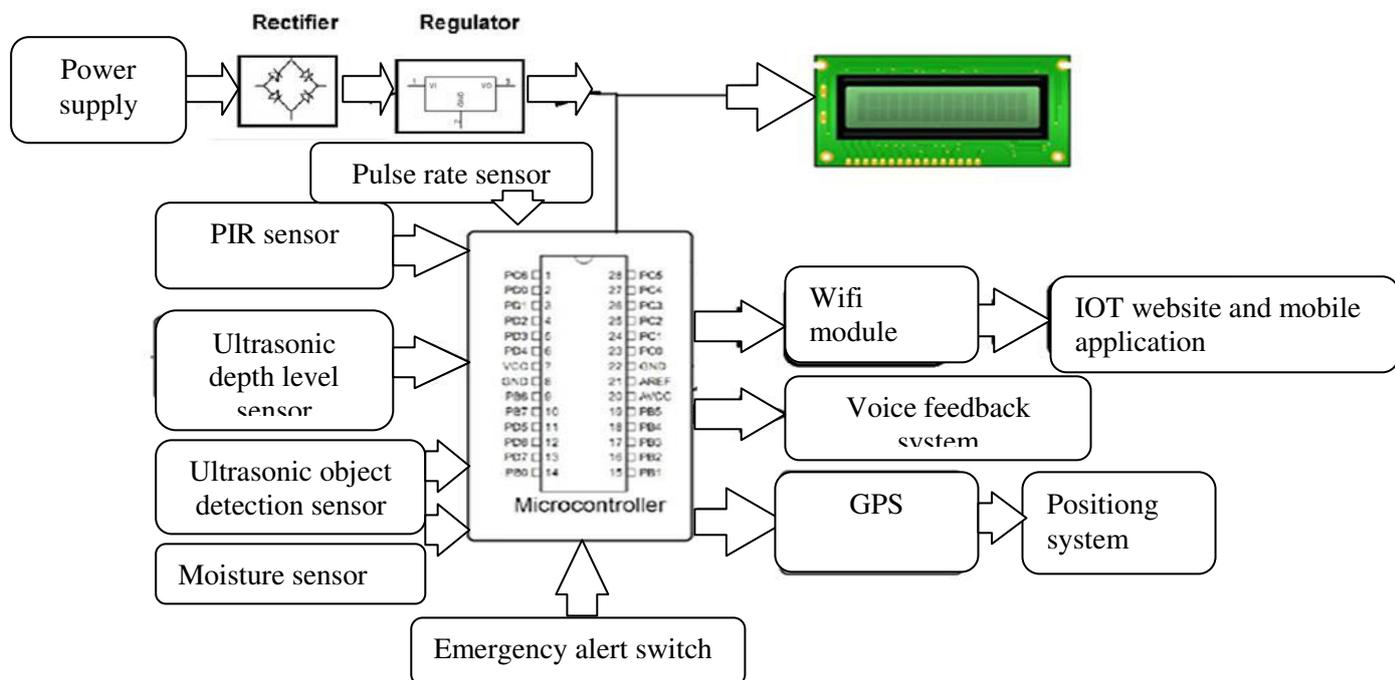
1. We WALK Smart Cane: We WALK is a smart cane developed by a Turkish startup. It features ultrasonic sensors to detect obstacles above chest level and includes a built-in voice assistant powered by Amazon's Alexa.
  - The cane connects to a smartphone app via Bluetooth, allowing users to receive navigation assistance, access location-based services, and control smart home devices.
  - WeWALK also integrates with Google Maps for navigation and provides haptic feedback to notify users of upcoming turns or points of interest.
2. XploR Smart Cane: XploR is a prototype smart cane developed by a team of engineers and designers in the UK. It incorporates ultrasonic sensors to detect obstacles and features a voice-controlled GPS navigation system.
  - The cane uses a combination of auditory and haptic feedback to guide users along their chosen route, providing directions and alerts for obstacles in real-time.
  - XploR aims to improve the mobility and independence of blind and visually impaired individuals by providing them with reliable navigation support in various environments.
3. SmartCane: SmartCane is a device developed by researchers at the Indian Institute of Technology Delhi (IIT Delhi). It utilizes ultrasonic sensors to detect obstacles in the user's path and provides feedback through vibrations.
  - While SmartCane does not include a voice module, it offers tactile feedback to alert users to obstacles within their vicinity, enabling them to navigate safely and independently.
4. Canetroller: Canetroller is a prototype smart cane developed by researchers at the University of California, San Diego (UCSD). It features a combination of ultrasonic sensors, cameras, and a voice module to provide navigation assistance and object detection.
  - The cane's voice module communicates information about detected obstacles and provides directions to help users navigate their surroundings with confidence.

## III. PROPOSED METHODOLOGY

1. Sensor Module:
  - a. The Smart Cane is equipped with various sensors such as ultrasonic, infrared, or LiDAR sensors to detect obstacles and hazards in the user's path.
  - b. These sensors continuously scan the surrounding environment and provide feedback to
2. the cane's control unit.
3. Control Unit:
  - a. The control unit processes the data received from the sensors in real-time and determines the appropriate actions to be taken.
  - b. It utilizes algorithms to analyze the sensor data and identify obstacles, drop-offs, and other potential hazards.
  - c. The control unit also interfaces with the voice module to provide audio feedback and

4. instructions to the user.
5. Voice Module:
  - a. The voice module is responsible for communicating important information to the user in a clear and concise manner.
  - b. It can provide auditory alerts for detected obstacles, directions for navigation, and other relevant information.
  - c. The voice module may support multiple languages and customizable settings to cater to
6. individual preferences.
  - a. 4. Connectivity Options:
  - b. The Smart Cane may include connectivity options such as Bluetooth or Wi-Fi, allowing it to synchronize with smartphones or other devices.
  - c. This connectivity enables additional features such as GPS navigation, remote assistance,
7. and data logging for analysis and improvement.
  - a. 5. Ergonomic Design:
  - b. The Smart Cane is designed to be lightweight, ergonomic, and easy to use, ensuring comfort and convenience for the user.
  - c. It retains the familiar form factor of a traditional cane, with added functionality
8. seamlessly integrated into its design.

#### IV. BLOCK DIAGRAM



Block Diagram of Smart Cane System for Visually Impaired and Blind People with Voice Module

#### V. EXPLANATION

- The proposed "Smart cane system for visually impaired and blind people with voice module" project offers a comprehensive solution .
- To increase the life quality of blind individuals and Promotes greater independence by enabling people to perform



the tasks By integrating advanced technologies, including IOTsensors and voice feedback mechanisms, the system aims to mitigate the risks associated with Mobility system and navigation system.

- The project consists of multiple components, each playing a crucial role in ensuring a collecting information and secure environment for the blind individuals .
  - The block diagram for the "Smart cane system for visually impaired and blind people with voice module".
- project can be summarized as follows:
- **Reset Input Devices:**
- **Start/Button:** The start/reset button serves as an input trigger for the system to initiate the sensors operations and .
- **Sensors:** Infrared Sensor, Ultrasonic sensor motion sensors, detect patient presence, and movement within the hospital.
- **Control Unit:** Arduino: Acts as the main control unit that receives inputs from the IoT sensors and coordinates the operation of the system, including ground depth analysis .
- **Audio playback system :** The voice feedback system gain signal from microprocessor and gives voice assistance through the speaker to th blind individual and it is categorised by object detection, human detection,ground depth and moisture detection .
- **Emergency switch :**Incase the blind individual facing any critical situation at that time ,the emergency switch helps and gives guidance to individual and send message to family members .
- **16x2 LCD Display:** Provides real-time information about the system's status, including patient occupancy, environmental conditions, and sanitization progress.
- **Buzzer:** Generates audible alerts to notify hospital staff of emergencies or system malfunctions.

## VI. WORKING METHODOLOGY

The IoT-based guide assistance operates through a sophisticated interplay of various components, each fulfilling crucial roles in ensuring seamless blind individual transport and safety management in healthcare settings. IoT the heart of the system lies the Arduino, orchestrating the stretcher's operation by receiving inputs from sensors and executing corresponding actions. The PIR sensor detects the presence of a human, prompting the Arduino to activate further processes, such as ultrasonic detects objects. Concurrently, the ultrasonic sensor constantly scans the environment for obstacles, signalling the Arduino to adjust the stretcher's movement trajectory or issue alarms as necessary.

Facilitating connectivity is the Nod MCU, enabling the integration with the Internet of Things (IoT) ecosystem. Through this connection, data flows between the navigation system and the IoT platform, providing a foundation for remote monitoring and control. Healthcare professionals leverage a dedicated mobile application interfaced with the IoT platform to oversee navigation operations remotely. From adjusting movement parameters to initiating collection information, the mobile app empowers staff with real-time insights and control, fostering efficiency and elevating patient care standards. With its seamless integration of advanced technologies, the IoT-based automatic message sending streamlines about blind individual navigation transportation and safety management, promising enhanced safety and comfort within healthcare facilities.

## VII. FUTURE SCOPE

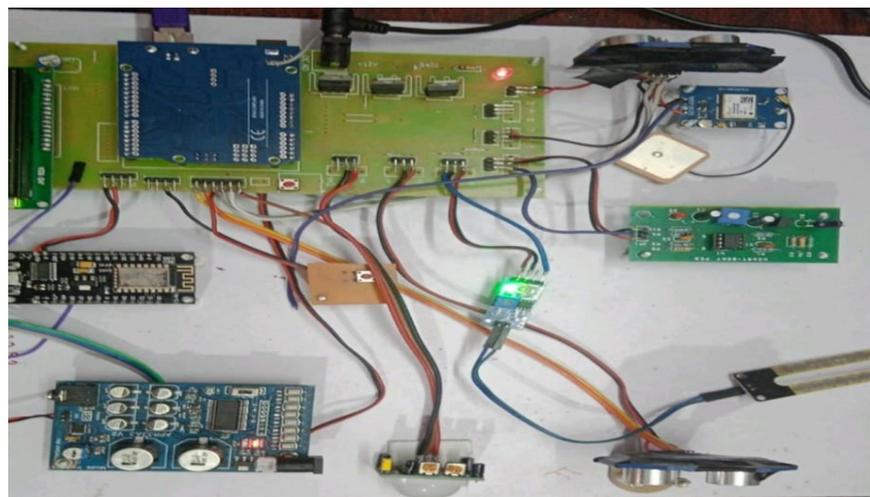
The future scope of The "Smart Cane System for Visually Impaired and Blind People with Voice Module" holds significant potential for future development and application within the assistive technology landscape. Here are several aspects indicating its future scope:

1. **Technological Advancements:** As technology continues to advance, the capabilities of the smart cane system are likely to improve. This could involve enhancements in sensor technology, voice recognition, connectivity options, and battery efficiency, making the device more effective and user-friendly.
2. **Integration with Artificial Intelligence (AI):** Integration with AI algorithms could enable the smart cane system to provide more personalized assistance to users. AI can analyze data from various sensors to identify patterns, predict obstacles, and offer proactive guidance to users, thereby enhancing their mobility and safety.
3. **Expanded Features and Functionality:** Future iterations of the smart cane system may incorporate additional

features and functionalities to address the diverse needs of visually impaired individuals. This could include navigation assistance, object recognition, indoor mapping, real-time feedback on environmental conditions, and integration with other smart devices and applications.

5. **Customization and User Experience:** There's potential for the development of customizable interfaces and user experiences tailored to the preferences and specific requirements of individual users. This could involve adjustable settings for voice commands, sensitivity of obstacle detection, and feedback mechanisms to accommodate varying levels of visual impairment.
6. **Accessibility and Affordability:** Efforts to make the smart cane system more accessible and affordable could broaden its adoption among visually impaired individuals worldwide. This could involve collaborations with organizations, governments, and technology companies to reduce production costs, improve distribution networks, and ensure equitable access to assistive technol

## OUTCOME



**Fig9.1 Experimental setup**

## IX. CONCLUSION

In conclusion, the "Smart Cane System for Visually Impaired and Blind People with Voice Module" represents a groundbreaking advancement in assistive technology, offering a seamless and efficient solution to address the challenges faced by visually impaired individuals in navigating their surroundings safely and independently. By integrating ultrasonic sensors, IoT connectivity, and a voice module, the system enhances safety, promotes independence, and contributes to an advanced healthcare environment. With its ability to provide real-time alerts, remote control functionality, and centralized control, the system stands as a beacon of hope for visually impaired individuals, offering a transformative tool to improve their quality of life and foster greater autonomy in their daily lives

## REFERENCES

1. (ICSIDEMPC), Aurangabad, India, 2020, pp. 200-201, doi: 10.1109/ICSIDEMPC49020.2020.9299646. [1] World Health Organization, Visual Impairment and Blindness, Fact sheet N 282, Oct 2014.
2. S. Vaibhav, Smart Cane for the Visually Impaired; Design and Controlled Field Testing of an Affordable Obstacle Detection System, 12th International Conference on Mobility and Transport for Elderly and Disabled Persons, 2010. 550 2019 IEEE Region 10 Conference (TENCON 2019)



3. G. Gaikwad, H. K. Waghmare, Smart Cane Indicating a Safe free Path to Blind People Using Ultrasonic Sensor, , International Journal on Recent and Innovation Trends in Computing and Communication, vol. 4, no. 2, pp. 179-183, Feb. 2016.
4. J. Sakhardande, P. Pattanayak, M. Bhowmick, Smart Cane Assisted Mobility for the Visually Impaired, International Journal of Computer Electrical Automation Control and Information Engineering, vol. 6, o. 10, pp. 1262-1265, 2012.
5. M. H. Wahab, A. A. Talib, H. A. Kadir, A. Johari, A. Noraziah, R. M. Sidek, A. A. Mutalib, Smart Cane; Assistive Cane for Visually-impaired People, IJCSI International Journal of Computer ScienceIssues, vol. 8, no. 4, pp. 21-27, Jul. 2011.
6. Agarwal, D. Kumar, A. Bhardwaj, Ultrasonic Stick for Blind, International Journal Of Engineering And Computer Science, vol. 4, no. 4, pp. 11375-11378, Apr. 2015.
7. Badamasi, Yusuf Abdullahi, The working principle of an Arduino, 2014 11th International Conference on Electronics, Computer and Computation (ICECCO). IEEE, 2014.
8. Alkadhim, Saif Aldeen , Aboud, Sarah, . LIGHT SENSOR TO SWITCH ON A LIGHT OR ANY DEVICE LDR. ,10.13140/RG.2.2.27258.54724.
9. Palee, Rabin, and SupachateInnet, Point to point distance measurement using ultrasonic for excellent stick.,2006.
10. Bousbia-Salah, Mounir, et al, An ultrasonic navigation system for blind people, 2007 IEEE International Conference on Signal Processing and Communications. IEEE, 2007.
11. Eriksson, Jakob, et al, The pothole patrol: using a mobile sensor network for road surface monitoring, Proceedings of the 6th international conference on Mobile systems, applications, and services. ACM, 2008.
12. Yuchun, Ma, et al, General application research on GSM module, 2011 International Conference on Internet Computing and Information Services. IEEE, 2011.
13. Jamieson, Susan, Likert scales: how to (ab) use them, Medical education 38.12: 1217-1218, 2004.



INTERNATIONAL  
STANDARD  
SERIAL  
NUMBER  
INDIA



# INTERNATIONAL JOURNAL OF MULTIDISCIPLINARY RESEARCH IN SCIENCE, ENGINEERING AND TECHNOLOGY

| Mobile No: +91-6381907438 | Whatsapp: +91-6381907438 | [ijmrset@gmail.com](mailto:ijmrset@gmail.com) |

[www.ijmrset.com](http://www.ijmrset.com)