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Fault Detection in PV System Using Gradient Boost Tree Algorithm

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ABSTRACT: Solar photovoltaic (PV) systems have emerged as a prominent source of renewable energy. However, their performance can be hindered by various factors, including faults within the PV modules or the overall system. Rapid and accurate detection of these faults is crucial for maintaining optimal energy production and ensuring system safety. This study proposes a novel approach for Solar Fault Detection using gradient boost tree algorithm. The proposed system leverages the power of deep learning techniques to automatically analyze images of solar panels and identify potential faults. A comprehensive dataset of annotated solar panel images is used for training the model. The dataset includes images captured under various lighting conditions and angles to account for real-world scenarios.

KEYWORDS: Solar photovoltaic (PV) system, Gradient Boost Tree algorithm, Renewable Energy, Solar panels

1. INTRODUCTION

The rapid adoption of solar photovoltaic (PV) systems as a key source of renewable energy has significantly contributed to the global transition towards sustainable power generation. However, the reliable performance of these systems is susceptible to various factors, including degradation, environmental wear, and faults within the PV modules or the overall system. Timely and accurate detection of these faults is critical for ensuring optimal energy production and safeguarding the longevity of the solar installation. In response to this challenge, this study introduces a novel approach for Solar Fault Detection employing advanced image processing techniques, specifically leveraging gradient boost tree algorithm. This cutting-edge methodology offers a promising solution to automate the identification of faults within solar panels.

The efficiency of solar PV systems is contingent on the integrity of individual PV modules. Common faults such as micro cracks, hot spots, shading effects, and soiling can lead to significant energy losses if left undetected. Traditional methods of fault detection often rely on manual inspection, which can be time-consuming, labour-intensive, and prone to human error. As the scale of solar installations continues to grow, there is an escalating need for automated, accurate, and real-time fault detection systems. The primary aim of this research is to develop a robust and efficient Solar Fault Detection system that can autonomously analyze images of solar panels and identify potential faults. This system holds the potential to revolutionize the maintenance and management of solar PV installations by providing a rapid and accurate means of fault identification.

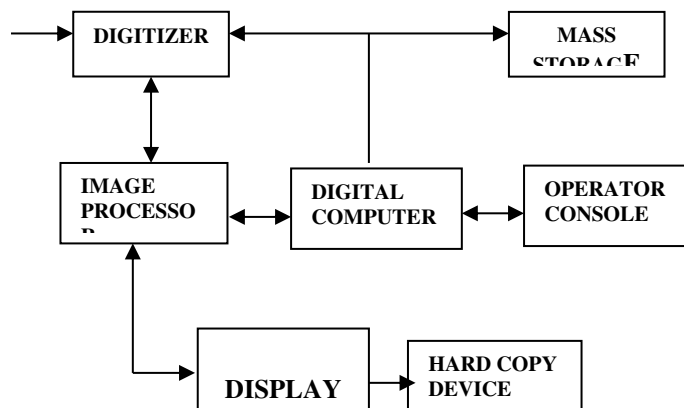


Fig.1 Block Diagram for Image Processing System



In this study sets out to make a significant contribution to the field of solar energy technology by introducing an innovative approach to fault detection.[Through the integration of advanced image processing and deep learning techniques, this system promises to enhance the efficiency, reliability, and sustainability of solar PV systems, ultimately advancing the global transition towards cleaner, more sustainable energy sources.

A) IMAGE PROCESSING

The term digital image refers to processing of a two dimensional picture by a digital computer. In a broader context, it implies digital processing of any two dimensional data. A digital image is an array of real or complex numbers represented by a finite number of bits. An image given in the form of a transparency, slide, photograph or an X-ray is first digitized and stored as a matrix of binary digits in computer memory.

This digitized image can then be processed and/or displayed on a high-resolution television monitor. For display, the image is stored in a rapid-access buffer memory, which refreshes the monitor at a rate of 25 frames per second to produce a visually continuous[1].

B) FAULT DETECTION IN PV SYSTEM CIRCUIT

The processing of a two-dimensional image by a digital computer is referred to as "digital image." It refers to the digital processing of any two-dimensional data in a more general sense. An array of real or complex numbers represented by a finite amount of bits is called a digital picture. An image that is provided as an X-ray, slide, transparency, picture, or other format is first digitally converted and saved in computer memory as a binary digit matrix

A digitizer converts an image into a numerical representation suitable for input into a digital computer. Some common digitizers are

- * Microdensitometer
- * Flying spot scanner
- * Image dissector
- * Videocon camera
- * Photosensitive solid- state arrays.

IMAGE PROCESSOR

An image processor acquires stores, preprocesses segments, represents, recognizes, and interprets images before displaying or recording the finished product. The basic flow of an image processing system is shown in the block diagram that follows,

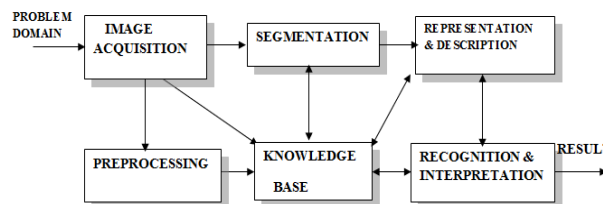


Fig.2 Block Diagram of Fundamental Sequence Involved In an Image Processing System

The process begins with picture acquisition using an imaging sensor and a digitizer to digitize the image, as shown in the illustration. The enhanced image is then provided as an input to the other operations in the preprocessing step, which comes next.

DIGITAL COMPUTER

Mathematical processing of the digitized image such as convolution, averaging, addition, subtraction, etc. are done by the computer.

MASS STORAGE

The secondary storage devices normally used are floppy disks, CD ROMs etc.

HARD COPY DEVICE

The hard copy device is used to produce a permanent copy of the image and for the storage of the software involved.



OPERATOR CONSOLE

The operator console consists of equipment and arrangements for verification of intermediate results and for alterations in the software as and when require. The operator is also capable of checking for any resulting errors and for the entry of requisite data.

IMAGE PROCESSING FUNDAMENTAL

Digital image processing refers processing of the image in digital form. Modern cameras may directly take the image in digital form but generally images are originated in optical form. They are captured by video cameras and digitalized. The digitalization process includes sampling, quantization. Then these images are processed by the five fundamental processes, at least any one of them, not necessarily all of them.[2]

C) IMAGE PROCESSING TECHNIQUES

This section gives various image processing techniques.

- Image Enhancement
- Image Revolution
- Image Analysis
- Image Compression
- Image Synthesis

IMAGE ENHANCEMENT

Image enhancement operations improve the qualities of an image like improving the image's contrast and brightness characteristics, reducing its noise content, or sharpen the details. This just enhances the image and reveals the same information in more understandable image. It does not add any information to it.

IMAGE RESTORATION

Image restoration like enhancement improves the qualities of image but all the operations are mainly based on known, measured, or degradations of the original image. Image restorations are used to restore images with problems such as geometric distortion, improper focus, repetitive noise, and camera motion. It is used to correct images for known degradations.

IMAGE ANALYSIS

Image analysis operations produce numerical or graphical information based on characteristics of the original image. They break into objects and then classify them. They depend on the image statistics. Common operations are extraction and description of scene and image features, automated measurements, and object classification. Image analyze are mainly used in machine vision applications.

IMAGE COMPRESSION

Image compression and decompression reduce the data content necessary to describe the image. Most of the images contain lot of redundant information, compression removes all the redundancies. Because of the compression the size is reduced, so efficiently stored or transported[3]. The compressed image is decompressed when displayed. Lossless compression preserves the exact data in the original image, but Loss compression does not represent the original image but provide excellent compression.

IMAGE SYNTHESIS

Image synthesis operations create images from other images or non-image data. Image synthesis operations generally create images that are either physically impossible or impractical to acquire.

D) IMAGE TYPES

There are several ways of encoding the information in an image.

- Binary image
- Gray-scale image



- Indexed image
- True color or RGB image

BINARY IMAGE

Each pixel is just black or white. Since there are only two possible values for each pixel (0, 1), we only need one bit-per pixel.

GRAYSCALE IMAGE

Each pixel is a shade of gray, normally from 0 (black) to 255(white). This range means that each pixel can be represented by eight bits, or exactly one byte. Other gray scale ranges are used, but generally they are a power of 2.

INDEXED IMAGE

An indexed image consists of an array and a color map matrix. The pixel values in the array are direct indices into a color map. By convention, this documentation uses the variable name X to refer to the array and map to refer to the color map.

TRUE COLOR OR RGB IMAGE

Each pixel has a particular color; that color is described by the amount of red, green and blue in it. If each of these components has a range 0–255, this gives a total of 256³ different possible colors. Such an image is a “stack” of three matrices; representing the red, green and blue values for each pixel. This means that for every pixel there correspond 3 values.

II. LITERATURE SURVEY

An efficient fault classification method in solar photovoltaic modules using transfer learning and multi-scale convolutional neural network. Photovoltaic (PV) power generation is one of the remarkable energy types to provide clean and sustainable energy. Therefore, rapid fault detection and classification of PV modules can help to increase the reliability of the PV systems and reduce operating costs. In this study, an efficient PV fault detection method is proposed to classify different types of PV module anomalies using thermo graphic images. The proposed method is designed as a multi-scale convolutional neural network (CNN) with three branches based on the transfer learning strategy. The convolutional branches include multi-scale kernels with levels of visual perception and utilize pre-trained knowledge of the transferred network to improve the representation capability of the network. To overcome the imbalanced class distribution of the raw dataset, the oversampling technique is performed with the offline augmentation method, and the network performance is increased. In the experiments, 11 types of PV module faults such as cracking, diode, hot spot, offline module, and other classes are utilized. [Deniz Korkmaz, Hakan Acikgoz,2022]

A Deep Learning Approach for Automated Fault Detection on Solar Modules Using Image Composites. Aerial inspection of solar modules is becoming increasingly popular in automatizing operations and maintenance in large-scale photovoltaic power plants. Current practices are typically time-consuming as they make use of manual acquisitions and analysis of thousands of images to scan for faults and anomalies in the modules. In this paper, we explore and evaluate the use of computer vision and deep learning methods for automating the analysis of fault detection and classification in large scale photovoltaic module installations. We generate composite images by overlaying the thermal and visible images to investigate improvements in detection accuracy of faint features related to faults on modules. Our main goal is to evaluate whether image processing with multi-wavelength composite images can improve both the detection and the classification performance compared to using thermal images alone. The hypothesis is that fusion of images acquired at different wavelengths (i.e., thermal infrared, red, green, and blue visible ranges) would enhance the multi-wavelength representation of faults and thus their histogram feature signatures. The results showed a successful detection and localization of faint fault features using composite images. However, the classification of the fault categories did not show significant improvements and needs continued investigation. [Anne Gerd Imenes; Nadia Saad Noori,2021].[4]

Photovoltaic system fault detection techniques: a review. Solar energy has received great interest in recent years, for electric power generation. Furthermore, photovoltaic (PV) systems have been widely spread over the world because of



the technological advances in this field. However, these PV systems need accurate monitoring and periodic follow-up in order to achieve and optimize their performance. The PV systems are influenced by various types of faults, ranging from temporary to permanent failures. A PV system failure poses a significant challenge in determining the type and location of faults to quickly and cost-effectively maintain the required performance of the system without disturbing its normal operation. Therefore, a suitable fault detection system should be enabled to minimize the damage caused by the faulty. In addition, an overview of recent techniques using different artificial intelligence tools with thermography methods is also presented [Ghada M. El- Banby1 Nada M. Moawad,2023]

III. EXISTING SYSTEM

In this existing system for the power produced by photovoltaic systems have great importance in the current global market. From small-scale applications to self-sufficient industries PV systems are planted for the generation and distribution of power. The main factors that need to be considered when setting up a PV plant are safety, cost efficiency and early fault detection techniques.

This review work displays the various types of faults seen in PV systems and briefs about the intelligent machine learning algorithms that are built to detect and classify these faults. Furthermore, with the extensive literature, this paper reviews various types of faults detected using different machine learning algorithms in photovoltaic systems which are shown to be reliable and effective to be implemented. The research work is not only bounded to reviewing the fault types with regard to the machine learning algorithms.

In conclusion, this study is disclosed to share all the valuable information to the scholars working in the field of photovoltaic systems.

DISADVANTAGES

- Complex machine learning models can be computationally expensive and may require significant computational resources. Deploying such models in resource-constrained environments, like remote solar installations, can be challenging.
- It well gather high-quality labeled data for fault detection in PV systems can be challenging and time-consuming
- Models heavily depend on the quality and representativeness of the training data. If the training data is incomplete, biased, or contains errors, the model's performance may be suboptimal.

IV. PROPOSED SYSTEM

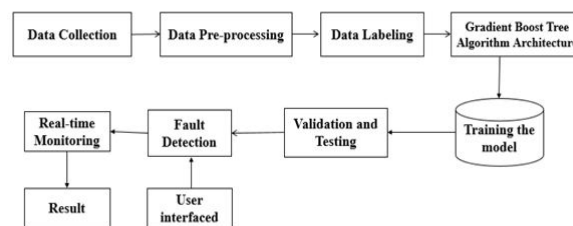
The proposed system for fault detection in PV (Photovoltaic) systems leverages the power of the Gradient Boost Tree Algorithm to enhance the reliability and efficiency of solar energy production. This system is designed to detect and diagnose faults or anomalies within PV systems, ensuring the continuous and optimal operation of solar panels. The system collects data from various sensors and monitors critical parameters such as voltage, current, temperature, and irradiance levels in real-time. These data points are then input into the Gradient Boost Tree Algorithm, which is a machine learning technique capable of learning complex patterns and trends in the data. In the training phase, historical data that includes both normal and faulty operating conditions of the PV system are used to train the algorithm. The Gradient Boost Tree Algorithm incrementally builds a model by combining multiple decision trees, each designed to detect specific types of faults, such as shading, partial module failures, or mismatched components. The weighted contributions of these trees are used to create an ensemble model with a high degree of accuracy. During the operational phase, the trained model is applied to the incoming sensor data to make real-time predictions. If any deviations from the expected or normal behavior are detected, the system triggers an alert or takes corrective actions. For instance, it can pinpoint the location and nature of a fault, allowing for prompt maintenance and reducing downtime. The advantages of this proposed system are its ability to adapt to changing environmental conditions and system components, as well as its capacity to identify faults early, ultimately improving the overall efficiency, reliability, and maintenance of PV systems. By harnessing the power of machine learning and the Gradient Boost Tree Algorithm, the system empowers solar energy stakeholders to proactively manage their PV installations, maximize energy production, and reduce operational costs, contributing to a more sustainable and resilient solar energy infrastructure.[5]



ADVANTAGES

- The system can identify faults at an early stage, allowing for timely maintenance and minimizing energy loss due to panel inefficiencies.
- The use of Gradient Boost Tree Algorithm automates the inspection process, reducing the reliance on manual inspections, which can be time-consuming and less accurate.
- Real-time monitoring, the system can detect faults as they occur, providing immediate alerts and enhancing overall system reliability.

A) SYSTEM ARCHITECTURE



ALGORITHM

GRADIENT BOOST TREE

Gradient Boosting is a powerful machine learning technique used for both regression and classification tasks, and it has found applications in various fields, including fault detection in photovoltaic (PV) systems. The Gradient Boosting Tree algorithm is a specific instance of gradient boosting that combines the strengths of decision trees and boosting techniques to improve predictive accuracy. It works by training a sequence of decision trees, where each new tree focuses on the errors made by the previous ones. In this process, Gradient Boosting assigns weights to each data point, allowing it to learn from misclassified samples and progressively refine its predictions.

This iterative nature of the algorithm leads to a strong predictive model, making it particularly well-suited for detecting faults in PV systems. By analyzing historical data and identifying deviations from expected performance, Gradient Boosting Tree algorithms can effectively pinpoint issues, such as equipment malfunctions or deteriorating solar panel efficiency, helping operators and maintenance teams maintain the optimal performance of PV installations. Gradient Boosting is a powerful machine learning algorithm used for both classification and regression tasks. It builds an ensemble of decision trees to create a strong predictive model. In the context of fault detection in a photovoltaic (PV) system, you can apply Gradient Boosting to identify and classify faults in the system.

1) DATA PREPARATION:

Collect and pre-process data from your PV system. This data should include features (inputs) that describe the system's behavior and a target variable (output) that indicates whether a fault is present or not.

2) ENSEMBLE LEARNING:

Gradient Boosting is an ensemble learning technique. It builds a model by combining multiple weak learners (usually decision trees) to create a strong predictive model. Each tree is trained sequentially, and the final prediction is a weighted sum of the predictions of all trees.

3) INITIALIZATION:

Initialize the model with a simple prediction, usually the mean of the target variable (for regression problems) or the most frequent class (for classification problems).

Compute the initial residual errors by comparing the initial predictions to the actual target values.



4) SEQUENTIAL TREE BUILDING:

Train a decision tree on the dataset with a primary focus on the remaining errors (residuals) from the previous step. Each tree is a weak learner that tries to correct the errors made by the current ensemble.

5) GRADIENT DESCENT:

Calculate the negative gradient of a loss function with respect to the model's prediction. This gradient indicates the direction in which the model should be updated to reduce the errors.

Update the model's prediction by a small fraction in the direction of the negative gradient. This is done to minimize the loss function.

6) WEIGHTED COMBINING:

Add the newly trained tree to the ensemble with a certain weight. The weight is determined by the learning rate, which controls the step size in the gradient descent.

Combine the predictions of all trees in the ensemble to make the final prediction.

7) ITERATIVE PROCESS:

Steps 4-6 should be repeated until a particular condition is met or for a predetermined number of iterations (determined by the number of trees in the ensemble, sometimes known as "n_estimators").

Model Evaluation:
Evaluate the performance of the Gradient Boosting model on a separate validation dataset to ensure it generalizes well to unseen data.

8) FAULT DETECTION:

Use the trained Gradient Boosting model to predict whether faults are present in the PV system based on the features provided. The model will provide a prediction or a probability score for each data point.

9) THRESH-HOLDING:

Define a threshold value for the predicted scores or probabilities. This threshold determines when a prediction is classified as indicating a fault or not.

10) REPORTING AND ACTION:

If the prediction exceeds the threshold, it is considered a fault detection, and appropriate actions can be taken to address the issue in the PV system.

V. MODULE LIST

1. Data Collection:
2. Data Pre-processing
3. Data Labelling
4. Gradient Boost Tree Architecture:
5. Training the Model
6. Validation and Testing
7. Fault Detection Process
8. User Interface
9. Real-time Monitoring



MODULE DESCRIPTION

1) DATA COLLECTION:

Gather a dataset of images of solar panels. This dataset should include a variety of images, including both healthy solar panels and panels with different types of faults (e.g., cracks, dirt, shading, hotspots, etc.).

2) DATA PRE-PROCESSING:

Pre-process the gathered photos to guarantee uniformity and improve their quality. This could entail normalizing pixel values, scaling photos to a standard size, and using noise reduction techniques to get rid of undesired artifacts.

3) DATA LABELLING:

Label each image in the dataset according to its condition, specifying whether it's a healthy panel or which type of fault it exhibits. This labelled dataset is crucial for supervised training of the Gradient Boost Tree model.

4) GRADIENT BOOST TREE ARCHITECTURE:

This module includes setting up the architecture for the Gradient Boost Tree model as described in the previous answer. In this case, the model will be trained to classify images as either healthy or showing a fault.

5) TRAINING THE MODEL:

The Gradient Boost Tree model is trained using the labelled image data. During training, the model learns to recognize patterns in the images that distinguish between healthy panels and faulty panels. It is crucial to pre-process the image data in a way that is compatible with the model's input requirements.

6) VALIDATION AND TESTING:

Split the dataset into training and validation sets to monitor the models performance during training. After training, evaluate the model on a separate testing dataset to assess its accuracy and generalization to unseen data.

7) FAULT DETECTION PROCESS:

In the fault detection process, users can upload images of solar panels through a web-based interface or by other means. The system then processes the uploaded image using the trained Gradient Boost Tree model.

8) USER INTERFACE:

The system provides a user-friendly interface that displays the results of the analysis to the user. It may indicate whether the panel is healthy or provide information about the type of fault detected.

9) REAL-TIME MONITORING:

For continuous fault detection, the system can be integrated into a real-time monitoring solution where images are processed as they are captured by cameras or drones. This ensures immediate fault detection and response.[4]

VI. SOFTWARE REQUIREMENTS

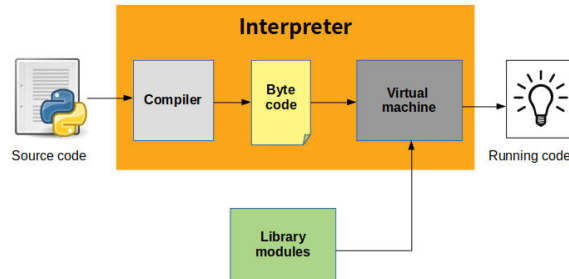
H/W SYSTEM CONFIGURATION:

- processor - Pentium – IV
- RAM - 4 GB (min)
- Hard Disk - 20 GB



S/W SYSTEM CONFIGURATION:

- Operating System : Windows 7 or 8



SOFTWARE ENVIRONMENT

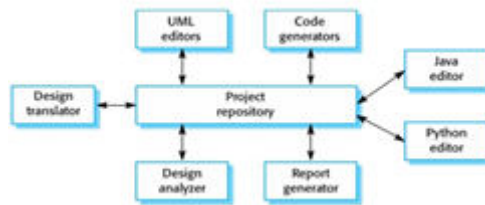


Fig.3 Repository architecture for an IDE

A) PYTHON TECHNOLOGY:

Python is an interpreter, high-level, general-purpose programming language. It supports multiple programming paradigms, including procedural, object-oriented, and functional programming. **Python** is often described as a "batteries included" language due to its comprehensive standard library.

B) PYTHON PROGRAMING LANGUAGE:

Python is a multi-paradigm programming language. Object-oriented programming and structured programming are fully supported, and many of its features support functional programming and aspect-oriented programming (including by Meta programming and met objects (magic methods)). Many other paradigms are supported via extensions, including design by contract and logic programming.

Python packages with a wide range of functionality, including:

- Easy to Learn and Use
- Expressive Language
- Interpreted Language
- Cross-platform Language
- Free and Open Source
- Object-Oriented Language
- Extensible
- Large Standard Library
- GUI Programming Support
- Integrated

Python strives for a simpler, less-cluttered syntax and grammar while giving developers a choice in their coding methodology. In contrast to Perl's "there is more than one way to do it" motto, Python embraces a "there should be one and preferably only one obvious way to do it" design philosophy. Alex Martelli, a Fellow at the Python Software Foundation and Python book author, writes that "To describe something as 'clever' is not considered a compliment in



the Python culture."[6]

C) THE PYTHON PLATFORM:

The platform module in Python is used to access the underlying platform's data, such as, hardware, operating system, and interpreter version information. The platform module includes tools to see the platform's hardware, operating system, and interpreter version information where the program is running. There are four functions for getting information about the current Python interpreter. `python_version()` and `python_version_tuple()` return different forms of the interpreter version with major, minor, and patch level components. `python_compiler()` reports on the compiler used to build the interpreter. And `python_build()` gives a version string for the build of the interpreter.

D) PRODUCTIVITY AND SPEED

It is a widespread theory within development circles that developing Python applications is approximately up to 10 times faster than developing the same application in Java or C/C++. The impressive benefit in terms of time saving can be explained by the clean object-oriented design, enhanced process control capabilities, and strong integration and text processing capacities. Moreover, its own unit testing framework contributes substantially to its speed and productivity.

E) BROAD APPLICATION

It is used for the broadest spectrum of activities and applications for nearly all possible industries. It ranges from simple automation tasks to gaming, web development, and even complex enterprise systems. These are the areas where this technology is still the king with no or little competence:

- Machine learning as it has a plethora of libraries implementing machine learning algorithms.
- Web development as it provides back end for a website or an app.
- Cloud computing as Python is also known to be among one of the most popular cloud-enabled languages even used by Google in numerous enterprise-level software apps.
- Scripting.
- Desktop GUI applications.

F) PYTHON COMPILER

The Python compiler package is a tool for analyzing Python source code and generating Python bytecode. The compiler contains libraries to generate an abstract syntax tree from Python source code and to generate Python bytecode from the tree. The compiler package is a Python source to bytecode translator written in Python. It uses the built-in parser and standard parser module to generate a concrete syntax tree. This tree is used to generate an abstract syntax tree (AST) and then Python bytecode. The full functionality of the package duplicates the built-in compiler provided with the Python interpreter. It is intended to match its behavior almost exactly.[8] Why implement another compiler that does the same thing? The package is useful for a variety of purposes. It can be modified more easily than the built-in compiler. The AST it generates is useful for analyzing Python source code.

The basic interface

The top-level of the package defines four functions. If you import compiler, you will get these functions and a collection of modules contained in the package.

compiler.Parse(buf)

Returns an abstract syntax tree for the Python source code in `buf`. The function raises Syntax Error if there is an error in the source code. The return value is a `compiler.ast`. Module instance that contains the tree.

compiler.parseFile(path)

Return an abstract syntax tree for the Python source code in the file specified by `path`. It is equivalent to `parse(open(path).read())`.

G) LIMITATIONS

There are some problems with the error checking of the compiler package. The interpreter detects syntax errors in two distinct phases. One set of errors is detected by the interpreter's parser, the other set by the compiler. The compiler package relies on the interpreter's parser, so it get the first phases of error checking for free. It implements the second phase itself, and that implementation is incomplete. For example, the compiler package does not raise an error if a



name appears more than once in an argument list: def f(x, x): ...
A future version of the compiler should fix these problems.

H) PERFORMANCE

A performance comparison of various Python implementations on a non-numerical (combinatorial) workload was presented at EuroSciPy '13.

Api Documentation Generators

Python API documentation generators include:

- Sphinx
- Epydoc
- HeaderDoc
- Pydoc

I) USES

Python has been successfully embedded in many software products as a scripting language, including in finite element method software such as Abaqus, 3D parametric modeler like Free CAD, 3D animation packages such as 3ds Max, Blender, Cinema 4D, Lightwave, Houdini, Maya, modo, MotionBuilder, Softimage, the visual effects compositor Nuke, 2D imaging programs like GIMP, Inkscape, Scribus and Paint Shop Pro, and musical notation programs like scorewriter and capella. GNU Debugger uses Python as a pretty printer to show complex structures such as C++ containers.

Esri promotes Python as the best choice for writing scripts in ArcGIS. It has also been used in several video games, and has been adopted as first of the three available programming languages in Google App Engine, the other two being Java and Go. Libber Office includes Python, and intends to replace Java with Python. Its Python Scripting Provider is a core feature since Version 4.0 from 7 February 2013.

VII. RESULT

With the PV module running, we estimate the temperature and irradiance. This work focuses on estimating temperature and irradiance by PV module. Simulations were conducted for a range of temperatures and irradiance conditions which is shown in fig.4.

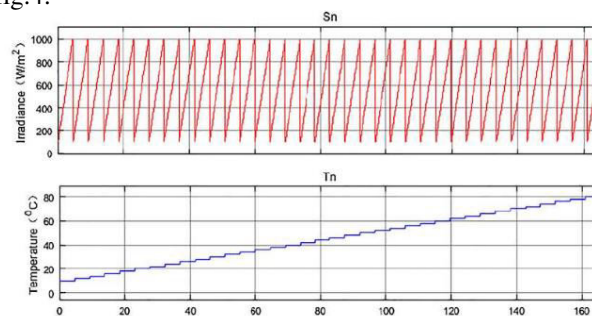


Fig.4 Operating irradiance and temperature of the simulated PV system.

When the string is being inspected, the operating current of the string is measured. It is feasible to determine whether the string is in the working state by measuring the operational current. The present values of the strings are nearly the same in a system where there are several strings made up of the same quantity and kind of modules.[7] An anomaly occurs when a string's current value deviates noticeably from the strings' other values. The current values of each string can be compared in order to find any irregularities. It is shown in fig.5.

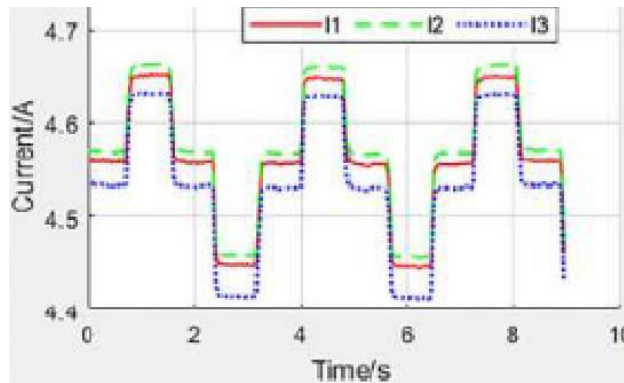


Fig.5 The PV String current

This approach controls the power flow between the PV system and the AC grid by obtaining the input voltage clamping of the inverter, also known as the PV array voltage (V_{pv}). By adjusting the LCC's firing angle for varying solar irradiation, the voltage clamping approach can help a PV array reach its maximum power point tracking (MPPT). The voltage and current characteristics of a solar PV panel at various irradiation levels are shown in fig.6.[9]

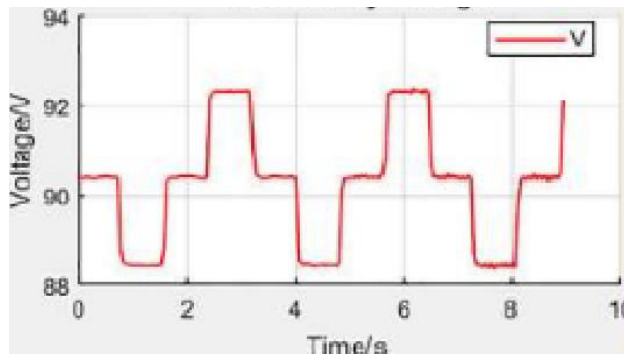


Fig.6 The PV Array Voltage

VII. CONCLUSION

In conclusion, solar panel fault detection using Gradient Boost Tree algorithm in image processing represents a ground breaking advancement in the field of renewable energy. This innovative technology offers an array of advantages, including early fault detection, increased energy yield, and cost savings, while minimizing downtime and prolonging the lifespan of solar panels. By automating the inspection process and leveraging the power of gradient boost, the renewable energy industry can enjoy a host of benefits, including reduced manual labour, improved safety, and a reduced carbon footprint. As the world increasingly relies on solar energy to combat climate change and meet growing energy demands, the ability to maintain the efficiency and reliability of solar panel installations is crucial. Solar panel fault detection using Gradient Boost Tree not only contributes to the sustainability of renewable energy but also enhances the return on investment for solar power projects. With its scalability, accuracy, and adaptability, this technology is poised to play a pivotal role in the widespread adoption of solar energy systems, making clean, sustainable power generation a reality for communities and businesses around the world.

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